

Reminders:

Parallel transport in P along path $\gamma: [0,1] \rightarrow M$ is a lift

$$\tilde{\gamma}_p: [0,1] \rightarrow P$$

s.t. $\pi \circ \tilde{\gamma}_p = \gamma$

$$\tilde{\gamma}_p'(t) \in H_A$$

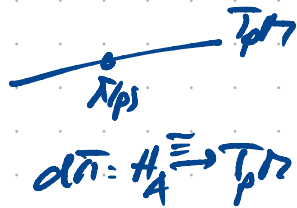
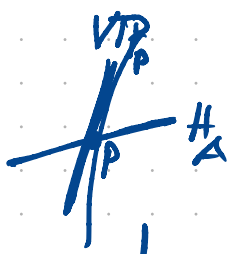
and

$$\tilde{\gamma}_p(0) = p$$

$$G \rightarrow P \downarrow M$$



A connection on P



$$\text{Par}_\gamma^A: P_{\gamma(0)} \rightarrow P_{\gamma(1)}$$

$$u \mapsto \tilde{\gamma}_u(1)$$

is G -invariant

Par. transport in

$$E = P \times_g V:$$

$$\text{Par}_\gamma^{A,E}: E_{\gamma(0)} \rightarrow E_{\gamma(1)}$$

$$[p, v] \mapsto [\text{Par}_\gamma^A(p), v]$$

well-defined because of G -invariance

$$\text{Par}_\gamma^A(pg) = \text{Par}_\gamma^A(p)g$$

$$\Sigma^*(P; V) \xrightarrow{d_A} \Sigma^*(P; V)$$

cov. cov.
eq. eq.

$$\cong \downarrow \qquad \qquad \qquad \downarrow \cong$$

$$\Sigma^*(\mathcal{M}; P; V) \xrightarrow{\bar{d}_A} \Sigma^*(\mathcal{M}; P; V)$$

(Defⁿ of \bar{d}_A)

See: \bar{d}_A satisfies Leibniz rule

$$d_A \stackrel{\text{Def}^n}{=} d \circ \text{pr}_{H_A}$$

$$\nabla_A := \bar{d}_A |_{T(P; V)}$$

is a cov. derivative (class).

Parallel transport of a cov. derivative:

If $E \rightarrow \mathcal{M} \xrightarrow{\gamma} \mathcal{M}$ ∇ cov. deriv. set $T(E)$

$$(\nabla_{\dot{\gamma}} s)(\gamma(t)) = 0 \quad (*)$$

then $s(\gamma(t)) \in E_{\gamma(t)}$ is said to arise from parallel transport along γ from $s(\gamma(0)) \in E_{\gamma(0)}$

$$\leadsto \text{Par}_Y^\Delta \in \text{Isom}(E_{\text{vec}}, E_{\text{lin}})$$

Prop: $\text{Par}_Y^{A, E} = \text{Par}_Y^{\Delta A}$

$E \rightarrow \mathbb{P}^s V$
 $s: G \rightarrow \text{Aut}(V)$
 group hom.

Natural $\left\{ \begin{array}{l} \Gamma(M; \mathbb{P}^s V) \\ \sim (\cong) \uparrow \\ \Gamma_s(\mathbb{C}P; V) \end{array} \right.$

Proof:

$$\begin{aligned} & (\Delta_{\dot{Y}(t)}^A)^s (Y(t)) \\ & \stackrel{\text{Def'n}}{=} (\bar{d}_A s) (\dot{Y}(t)) \\ & = \overline{d_A \hat{s}} (\dot{Y}(t)) \end{aligned}$$

\tilde{Y} horiz. lift

↑ here really we take an arbitrary lift projecting onto $\dot{Y}(t)$

$$\begin{aligned} & = [\tilde{Y}(t), d_A \hat{s} (\dot{Y}(t))] \\ & = [\tilde{Y}(t), ds (\dot{Y}(t))] \\ & \stackrel{\text{Def'n}}{=} [\tilde{Y}(t), \frac{d}{dt} s (\dot{Y}(t))] \end{aligned}$$

$$\left(\nabla_{\dot{\gamma}(t)}^A \hat{s} \right) (\gamma(t)) \stackrel{\text{Def'n}}{=} \left(\bar{d}_A \hat{s} \right) (\dot{\gamma}(t))$$

$$= \overline{d_A \hat{s}} (\dot{\gamma}(t))$$

↑ here really we take an arbitrary lift projecting onto $\dot{\gamma}(t)$

$$= [\tilde{\gamma}(t), d_A \hat{s} (\dot{\tilde{\gamma}}(t))] \stackrel{\text{Def'n}}{=} [\tilde{\gamma}(t), d \hat{s} (\dot{\tilde{\gamma}}(t))]$$

$$\stackrel{\text{Def'n}}{=} [\tilde{\gamma}(t), \frac{d}{dt} \hat{s} (\tilde{\gamma}(t))] \stackrel{\text{Def'n}}{=} [\text{Par}_{\tilde{\gamma}}^A (\tilde{\gamma}(0)), \frac{d}{dt} \hat{s} (\tilde{\gamma}(t))]$$

$$\stackrel{\text{Def'n}}{=} \left(\text{Par}_{\tilde{\gamma}}^{A, E} \left([\tilde{\gamma}(0), \frac{d}{dt} \hat{s} (\tilde{\gamma}(t))] \right) \right)$$

↑ path in V

↑ path from $\tilde{\gamma}(0)$ to $\tilde{\gamma}(t)$

$$\left(\nabla_{\dot{\gamma}(t)}^A \hat{s} \right) (\gamma(t)) = 0$$

$$\iff \frac{d}{dt} \hat{s} (\tilde{\gamma}(t)) = 0 \quad \forall t \in [a, b]$$

If $\frac{d}{dt} \hat{s}(\tilde{Y}(t)) = 0 \quad \forall t$, then $\hat{s}(\tilde{Y}(1)) = \hat{s}(\tilde{Y}(0))$ (x)

$$s(Y(1)) = \text{Par}_Y^{\Delta A} (s(Y(0)))$$

$$\text{if } \nabla_{Y(t)}^{\Delta A} s = 0$$

Oben

$$\text{Par}_Y^{A, E} (s(Y(0))) = [\text{Par}_Y^A (\tilde{Y}(0)), \hat{s}(\tilde{Y}(0))] \\ [\tilde{Y}(0), \hat{s}(\tilde{Y}(0))]$$

$$= [\tilde{Y}(1), \hat{s}(\tilde{Y}(1))]$$

$$\text{if (x) holds} \quad [\tilde{Y}(1), \hat{s}(\tilde{Y}(1))]$$

$$= s(Y(1))$$

$$\Rightarrow \text{Par}_Y^{A, E} (s(Y(0))) = s(Y(1)) \quad \text{if } \square$$

$$(x) \text{ holds} \iff \nabla_{Y(t)}^{\Delta A} s = 0$$

$$\text{Oben } \text{Par}_Y^{\Delta A} (s(Y(0))) = s(Y(1)) \quad \text{also, by def. of } \text{Par}_Y^{\Delta A}$$

Recall $E \rightarrow M$ a vector bundle

$$R^\nabla(v, w) = \nabla_v \nabla_w - \nabla_w \nabla_v - \nabla_{[v, w]}$$

defines curvature

$$R^\nabla \in \Gamma(\wedge^2 T^*M \otimes \text{End}(E))$$

Prop: If $E = P \times_S V$, A a connection on P ,

then

$$S_x: \mathfrak{g} \rightarrow \text{End}(V)$$

$$\begin{array}{ccc} \Gamma_G(P; V) & \xrightarrow{S_x \circ \nabla_A} & \Gamma_G(P; V) \\ \downarrow \cong & & \downarrow \cong \\ \Gamma(E) & \xrightarrow{R^{PA}} & \Gamma(E) \end{array}$$

Proof: If $\varphi \in \Gamma(P \times_S V)$, $\widehat{\varphi}$ lift to $\in \Gamma_G(P; V)$

$$(*) \quad (\nabla_v^A \varphi)_G = [\rho_* (d_A \widehat{\varphi})_p(\tilde{v})] \quad \text{where } d\tilde{\pi}(\tilde{v}) = v$$

$$(\varphi(x)) = [\rho_* \widehat{\varphi}(\rho)]$$

where $\tilde{\pi}(\rho) = x$

$$\Rightarrow (R_x^{\nabla A} (v_x, w_x) \varphi)(\alpha)$$

v, w
vector
fields,

$$= R_x^{\nabla A} (v_x, w_x) [p, \hat{\varphi}(\varphi)]$$

\tilde{v}, \tilde{w}
horizontal
lifts w.r.t

$$\stackrel{\alpha}{=} [p, (\tilde{v}_p, \tilde{w}_p, \hat{\varphi})$$

$$d\pi|_{\mathbb{H}_A} : \mathbb{H}_A \rightarrow T\mathbb{R}^n$$

$$- \tilde{w}_p \cdot (\tilde{v}, \hat{\varphi}) - \widetilde{[v, w]}_p \cdot \hat{\varphi}(\varphi)]$$

$$= [p, ([\tilde{v}, \tilde{w}], \hat{\varphi} - \widetilde{[v, w]}_p \cdot \hat{\varphi})(\varphi)]$$

does not
need to
be horiz
(not in general
if \mathbb{H}_A is not
convex)

dif
 $\in \ker(d\pi)$
 $= VTP$

but

$$d\pi([\tilde{v}, \tilde{w}])$$

$$= [d\pi(\tilde{v}), d\pi(\tilde{w})]$$

$$= [v, w]$$

$$= d\pi(\widetilde{[v, w]})$$

$$= [p, (\pi_V([\tilde{v}, \tilde{w}]), \hat{\varphi})(\varphi)]$$

by defn
of
 ω_A

$$[p, \omega_A([\tilde{v}, \tilde{w}]) \# \hat{\varphi}]$$

$$d_A \omega_A = \mathcal{L}_A$$

$$\Rightarrow d_A \omega_A(\tilde{v}, \tilde{w})$$

$$= d\omega_A(\tilde{v}, \tilde{w})$$

$$\stackrel{\text{so}}{\Rightarrow} -\omega_A(\tilde{v}, \tilde{w}) + \tilde{v}\omega_A(\tilde{w}) - \tilde{w}\omega_A(\tilde{v})$$

$$= -[A \mathcal{L}_A(\tilde{v}, \tilde{w})] \# \hat{\varphi}$$

$$\mathcal{L}_A(\tilde{v}, \tilde{w}) \hat{\varphi}(\rho)$$

$$= \left. \frac{d}{dt} \right|_{t=0} \hat{\varphi}(\rho e^{t \mathcal{L}_A(\tilde{v}, \tilde{w})})$$

Equiv.
of $\hat{\varphi}$

$$\left. \frac{d}{dt} \right|_{t=0} \mathcal{S}(e^{-t \mathcal{L}_A(\tilde{v}, \tilde{w})}) \hat{\varphi}(\rho)$$

$$= -\mathcal{S}_* (\mathcal{L}_A(\tilde{v}, \tilde{w})) \hat{\varphi}(\rho)$$

$$= [\rho, \mathcal{S}_* (\mathcal{L}_A(\tilde{v}, \tilde{w})) \hat{\varphi}(\rho)]$$

$$\Rightarrow \mathcal{R}_*^{\Delta}(\tilde{v}, \tilde{w}) [\rho, \hat{\varphi}(\rho)]$$
$$= [\rho, \mathcal{S}_* (\mathcal{L}_A(\tilde{v}, \tilde{w})) \hat{\varphi}(\rho)]$$

